

# **EECS 20. Final Exam**

**May 20, 2003.**

Please use these sheets for your answer. **Write clearly and show your work on the sheets in the back.** Please check that you have 11 numbered pages.

Print your name and lab time below

Name: \_\_\_\_\_

Lab time: \_\_\_\_\_

Problem 1 (15):

Problem 2 (20):

Problem 3 (20):

Problem 4 (25):

Problem 5 (20):

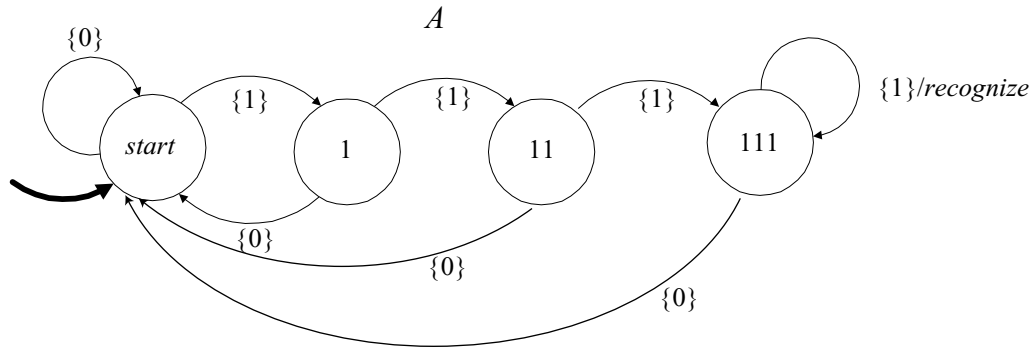
Problem 6 (10):

Problem 7 (10):

Total:

1. 15 points. 5 points for (a), 10 points for (b)

- (a) The deterministic machine  $A$  is like the *CodeRecognizer* machine studied in the text and in the homework.

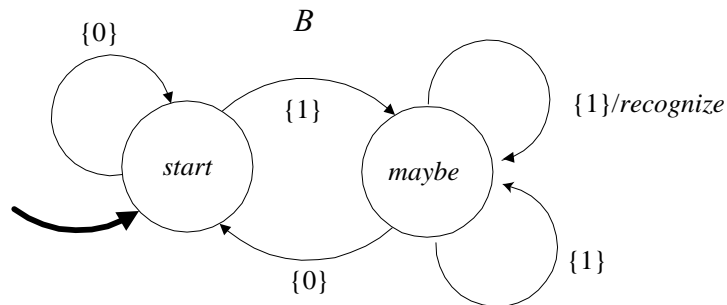


Let  $x$  denote an input signal and  $y$  the corresponding output signal. Complete the expression for  $y(n)$  below, ignoring stuttering inputs, (i.e. replace the  $\dots$  by an expression involving  $x$ )

$$\forall x \in \text{InputSignals}, \quad \forall n \in \text{Naturals}_0,$$

$$y(n) = \begin{cases} \text{recognize}, & \text{if } \dots \\ \text{absent}, & \text{otherwise} \end{cases}$$

- (b) Determine whether the non-deterministic machine  $B$  simulates  $A$  and write down the relevant simulation relation if it does.



2. **20 points. 5 points for (a), (b), 10 points for (c)** The input signal  $x$  and output signal  $y$  of an LTI system are related by the differential equation

$$\forall t \in \text{Reals}, \quad \dot{y}(t) + y(t) = x(t).$$

- (a) The frequency response of this system is

$$\forall \omega \in \text{Reals}, \quad H(\omega) =$$

and the *magnitude* and *phase* response for  $\omega = 0, \pm 1$ , and  $\omega \rightarrow \pm\infty$  are:

- (b) The impulse response of this system is

$$\forall t \in \text{Reals} \quad h(t) = \begin{cases} & , \text{ if } t < 0 \\ & , \text{ if } t > 0 \end{cases}$$

**Hint:** The Fourier transform of the signal  $x(t) = 0, t < 0; x(t) = e^{-t}, t \geq 0$  is  $\forall \omega, X(\omega) = [1 + i\omega]^{-1}$ .

- (c) Now consider an LTI system whose impulse response  $g = h * h$ , where  $h$  is as in (2b). Let  $G$  be the frequency response of this system. Then

$$\forall \omega \in \text{Reals}, \quad G(\omega) = ,$$

$$|G(1)| = , \quad \angle G(1) =$$

$$\forall t \in \text{Reals}, \quad g(t) = \begin{cases} & , \text{ if } t < 0 \\ & , \text{ if } t > 0 \end{cases}$$

3. **20 points, 4 points each part** Let  $M$  be a deterministic state machine with input and output alphabet  $\{0, 1, absent\}$ . State whether the following propositions are true or false.

(a) Suppose  $M$  has a *finite* number of states. Let  $y = (y(0), y(1), \dots)$  be the output signal corresponding to the input signal  $x = (0, 0, 0, \dots)$  (all zero sequence). Then the output signal  $y$  must be eventually periodic, i.e. there are integers  $N, p$  such that  $\forall n > N, y(n + p) = y(n)$ .

**Answer:**

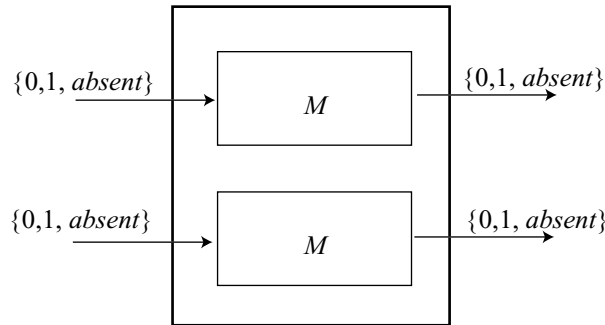
(b) Suppose the output signal  $y$  of  $M$  is related to its input signal  $x$  by:  $\forall n \geq 0,$

$$y(n) = \begin{cases} 1, & \text{if } x(0), \dots, x(n) \text{ contain an } \textit{unequal} \text{ number of 0s and 1s,} \\ 0, & \text{otherwise} \end{cases}$$

Then  $M$  has an *infinite* number of states.

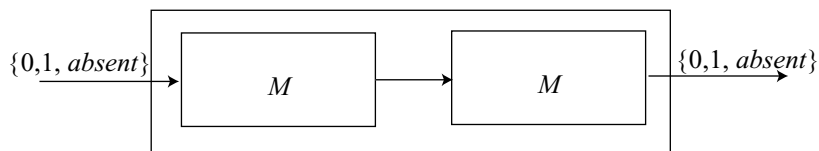
**Answer:**

(c) Suppose all the states of  $M$  are *reachable* (from the initial state). Then all states of the side-by-side composition of  $M$  with itself are reachable. The composition is shown below.



**Answer:**

(d) Suppose all the states of  $M$  are *reachable* (from the initial state). Then all states of the cascade composition of  $M$  with itself are reachable. The composition is shown below.



**Answer:**

(e) Suppose  $N$  is another deterministic state machine that simulates  $M$ . Then  $M$  simulates  $N$ .

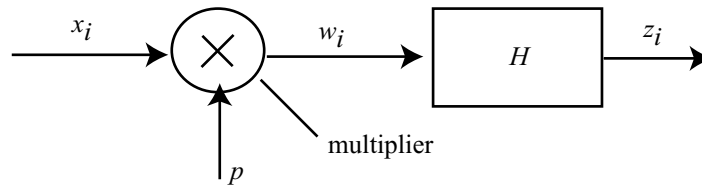
**Answer:**

4. **25 points, 5 points each part** In the block diagram below of a sampling and reconstruction system, the input signal  $x_i : \text{Reals} \rightarrow \text{Complex}$  is multiplied by the periodic impulse train  $p$  to produce the sampled signal  $w_i$ . Here

$$\forall t \in \text{Reals}, \quad p(t) = \sum_{n=-\infty}^{\infty} \delta(t - nT),$$

The ideal reconstruction filter has frequency response  $H$ :

$$\forall \omega, \quad H(\omega) = \begin{cases} T, & \text{if } |\omega| < \pi/T \\ 0, & \text{otherwise} \end{cases}$$



Assume below that the sampling frequency is  $f = 8,000$  Hz,  $T = 125\mu\text{s}$ .

**Note: Answers to questions below do not require much calculation**

- (a) The Fourier transform of  $p$  is

$$\forall \omega \in \text{Reals}, \quad P(\omega) = \quad .$$

- (b) In terms of  $X_i$ , the Fourier Transform of  $x_i$ , the Fourier Transform of  $w_i$  is

$$\forall \omega \in \text{Reals}, \quad W_i(\omega) = \quad .$$

and the Fourier Transform of  $z_i$  is

$$\forall \omega \in \text{Reals}, \quad Z_i(\omega) = \quad .$$

(c) Suppose  $\forall t, x_1(t) = \cos(2\pi \times 1000t)$ . Then  $\forall \omega \in \mathbf{Reals}$ ,

$$X_1(\omega) =$$

$$W_1(\omega) =$$

$$Z_1(\omega) =$$

(d) Suppose  $\forall t, x_2(t) = \cos(2\pi \times 7000t)$ . Then  $\forall \omega \in \mathbf{Reals}$ ,

$$X_2(\omega) =$$

$$W_2(\omega) =$$

$$Z_2(\omega) =$$

(e) Suppose  $\forall t, x_3(t) = \cos(2\pi \times 1000t) - \cos(2\pi \times 7000t)$ . Then  $\forall \omega \in \mathbf{Reals}$ ,

$$Z_3(\omega) =$$

and  $\forall t \in \mathbf{Reals}$ ,

$$z_3(t) =$$

5. **20 points, 5 points each part** The step input for a continuous time system is defined as  $x(t) = 0, t < 0, x(t) = 1, t \geq 0$ ; and for a discrete time system it is defined as  $x(n) = 0, n < 0, x(n) = 1, n \geq 0$ .

(a) If the impulse response of a continuous time LTI system is

$$\forall t, \quad h(t) = \begin{cases} 0, & t < 0 \\ e^{-t}, & t \geq 0 \end{cases}$$

its step response is

$$s(t) = \begin{cases} & , \quad t < 0 \\ & , \quad t \geq 0 \end{cases}$$

(b) If the impulse response of a continuous time LTI system is

$$h(t) = \begin{cases} e^{-|t|}, & t < 0 \\ 0, & t \geq 0 \end{cases}$$

its step response is

$$s(t) = \begin{cases} & , \quad t < 0 \\ & , \quad t \geq 0 \end{cases}$$

(c) If the impulse response of a discrete time LTI system is

$$h(n) = \begin{cases} 1, & n = 0, 1, 2 \\ 0, & \text{otherwise} \end{cases}$$

its step response is

$$s(n) = \begin{cases} & \\ & \\ & \end{cases}$$

(d) If the impulse response of a discrete time LTI system is

$$h(n) = \begin{cases} 1, & n = 1, 2, 3 \\ 0, & \text{otherwise} \end{cases}$$

its step response is

$$s(n) = \begin{cases} & \\ & \\ & \end{cases}$$

6. **10 points, 3 points for (a)-(c), 1 point for (d)** For each continuous time signals  $x_i$ , write down its Fourier transform  $X_i$

(a)  $\forall t, x_1(t) = e^{i20t}$ .

$$\forall \omega, X_1(\omega) =$$

(b)  $\forall t, x_2(t) = 1, |t| < T; x_2(t) = 0, |t| > T$ .

$$\forall \omega, X_2(\omega) =$$

(c)  $\forall t, x_3(t) = x_1(t) \times x_2(t)$ , where  $x_1, x_2$  are as above.

$$\forall \omega, X_3(\omega) =$$

(d) The unit of  $\omega$  above is



7. **10 points** For each of the following discrete-time systems with input signal  $x$  and output signal  $y$ , state whether it is linear (L), time-invariant (T), linear and time-invariant (LTI), or none (N).

$\forall n, y(n) = x(2 - n)$  **Answer:**

$\forall n, y(n) = [x(n - 1)]^2$  **Answer:**

$\forall n, y(n) = \sum_{m=-\infty}^{\infty} 0.5^{|m|} x(n - m)$  **Answer:**

$\forall n, y(n) = x(2 - n) + x(n - 2)$  **Answer:**

$\forall n, y(n) = n^2 x(n)$  **Answer:**

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